

A grayscale image of a Fujitsu Primergy server rack, viewed from a low angle. The rack is filled with server components, including multiple hard drive bays on the left and a control panel on the right. The text is overlaid on the image.

# Linux firmware for iRMC controller on Fujitsu Primergy servers

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## Table of content

### ① Fujitsu Primergy servers family

- What is iRMC

- Software - ServerView Suite

- Open standards: IPMI protocol and others

- iRMC internals

- Demo: WebIF and IPMI

### ② Road to Linux: from iRMC S1/ThreadX to iRMC S4/Linux

- Early days - ThreadX : S1 - S2/S3

- Migration to Linux: S4

- Demo: RemoteManager - bug-to-bug compatible

## Fujitsu Primergy Servers

Lineage of x86-based servers:

Blade (BX), Rack (RX), Tower (TX) and Cloud (CX).



## iRMC S4 in the wild





# iRMC - integrated Remote Management Controller

## ARM-based SoC

Emulex Pilot3 iBMC ASIC

Integrated BMC

Super I/O

Graphics controller

KVMS: Remote Keyboard, Video, Mouse and Storage

CPU: 32-bit 400MHz ARM9 processor with MMU.



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### Control x86 hardware

Work in progress: iRMC-264, iRMC-265, iRMC-266

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### Control x86 hardware

Work in progress, but if x86 hardware is supported...

## iRMC basic features

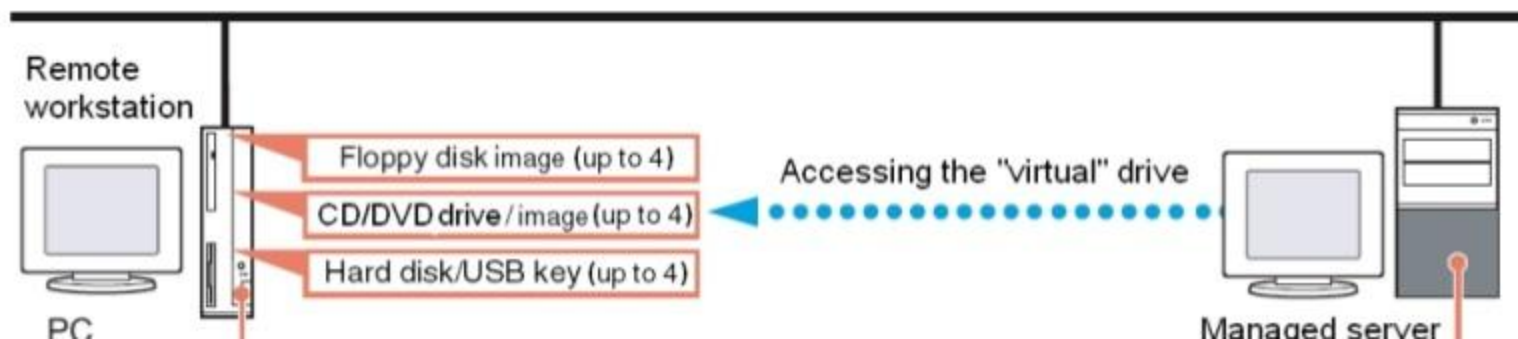
- Web access (own web-server)
- Security (SSL and SSH included)
- ServerView suite Integration
- Power management
- SNMPv1/v2c/v3 support
- Text console redirection
- “Headless” system operation





## iRMC advanced features

- Advanced Video Redirection (AVR)
- Virtual Media
- Embedded Lifecycle Management (eLCM)



## Open standards

**<HTML>**

**http://**



### Intelligent Platform Management Interface

IPMI - standardized, abstract, message-based interface between BMC and intelligent hardware for platform management. Key component of system.

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Web-based control interface.

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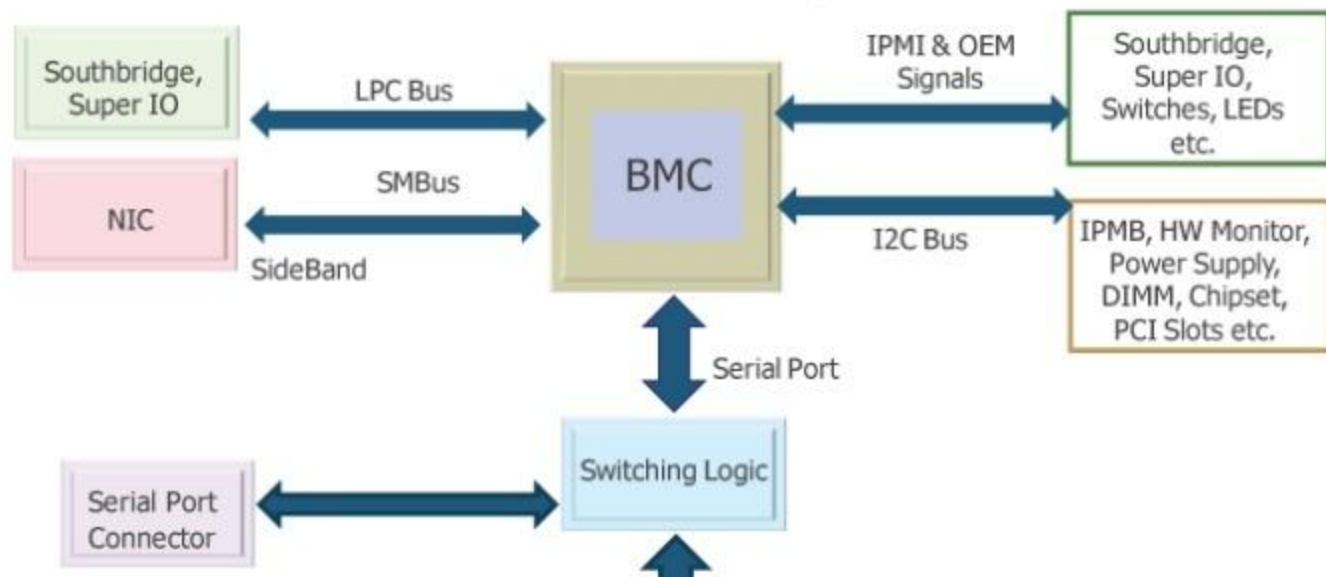
Web-based control interface.

### SNMP ver 1/2x/3



## IPMI - key interface of a system

### IPMI Block Diagram



## Demo 1

Web interface: AVR, VirtualMedia, remote boot

### **Scenario 1: AVR, show boot settings**

AVR: show Windows, Start LCM Custom Image, AVR: Show Linux

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### Scenario 1: AVR, show boot settings

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### Scenario 2: IPMI - via ipmitool

```
$ ipmitool -U admin -P admin -H 192.168.1.1 -I lanplus [command line]
```

command line variants:

- chassis status
- lan print

iRMC S1 - S2/S3 OS



## Pro

- Advanced Real-Time Operation System
- Small footprint
- Fast performance



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- Advanced Real-Time Operation System
- Small footprint
- Fast performance

## Contra

- Lack of available developers



## Why Linux



## Why Linux



Cost of development and support

- More developers available

## Main challenges

### Backward compatibility

- Same interfaces (UI, protocols)
- Binary firmware upgrades



## Main challenges

### Backward compatibility

- Same interfaces (UI, protocols)
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### Code re-use



## Demo 2: OpenSSH + RemoteManager

Interface ~~bug to bug~~ byte to byte identical to ThreadX.

```
*****
*   Welcome to PRIMERGY Remote Manager   *
*   Firmware Revision 98.10a (1.00)      *
*   SDR 3.16 ID 0401 TX1320M1           *
*   Firmware built Nov  5 2015 16:35:12 CET *
*****
```

```
System Type : PRIMERGY TX1320 M1
System ID   : YLXLXXX36
System Name  : SUT-PW
System OS    : Windows Server 2016 Technical Preview 3 Standard
System Status: OK (Identify LED is OFF)
Power Status : Off
Asset Tag    : System Asset Tag
```

Main Menu

- (1) System Information...
- (2) Power Management...
- (3) Enclosure Information...



## iRMC Firmware components

### Free and Open Source Software

- Linux Kernel
- U-Boot bootloader
- Busybox
- GNU Glibc
- Net-SNMP
- OpenSSH



## iRMC Firmware components

### Free and Open Source Software

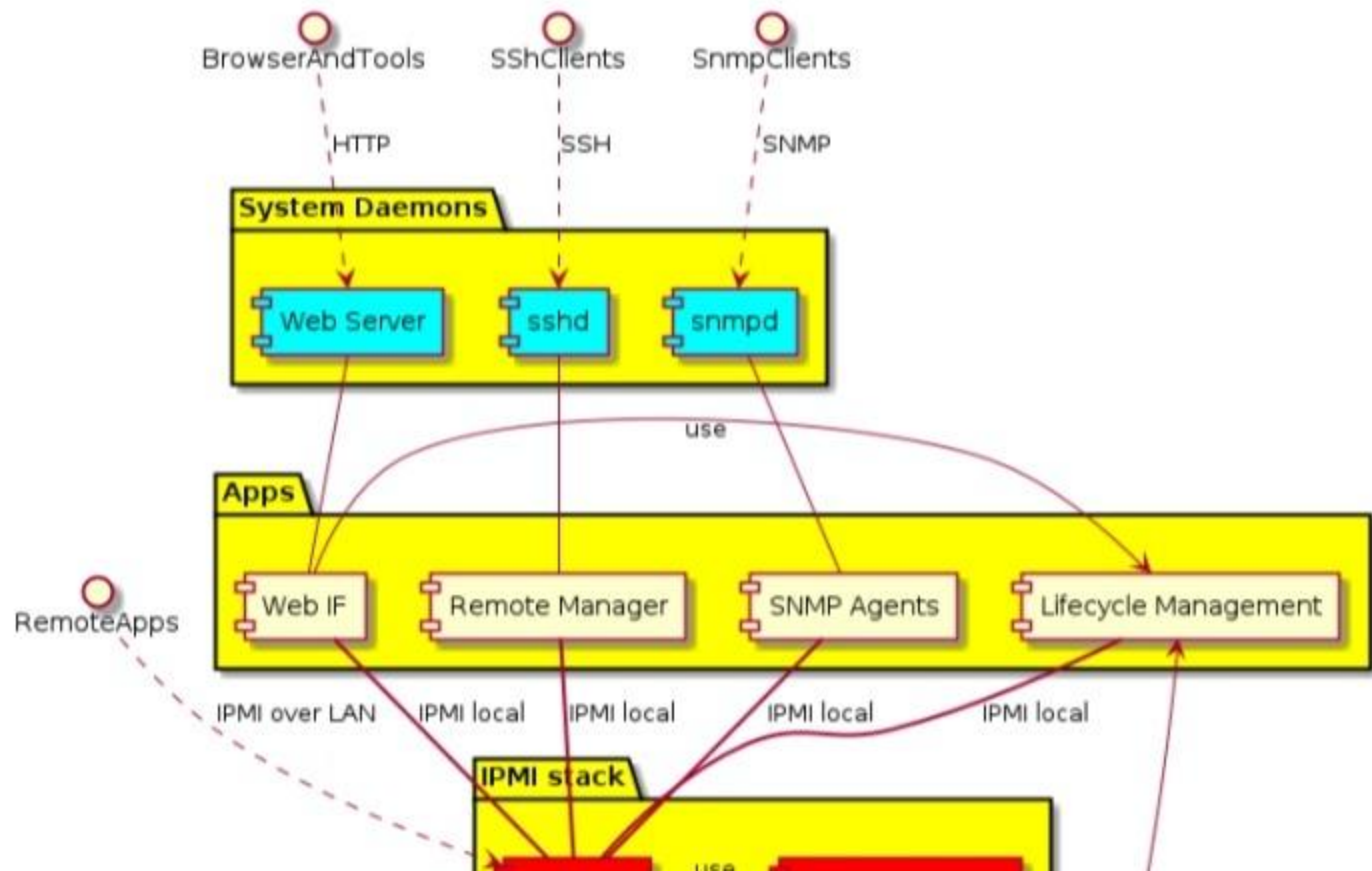
- Linux Kernel
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- Net-SNMP
- OpenSSH



### Closed source

PROPRIETARY

# iRMC firmware internals



## Development environment

### **LXC containers + X2go for developers**

The same environment for all to build and debug.

Read-only root filesystem on container.

Debian GNU/Linux based.

### **Custom package system**

Used only in development and build process.

Not used for updates.

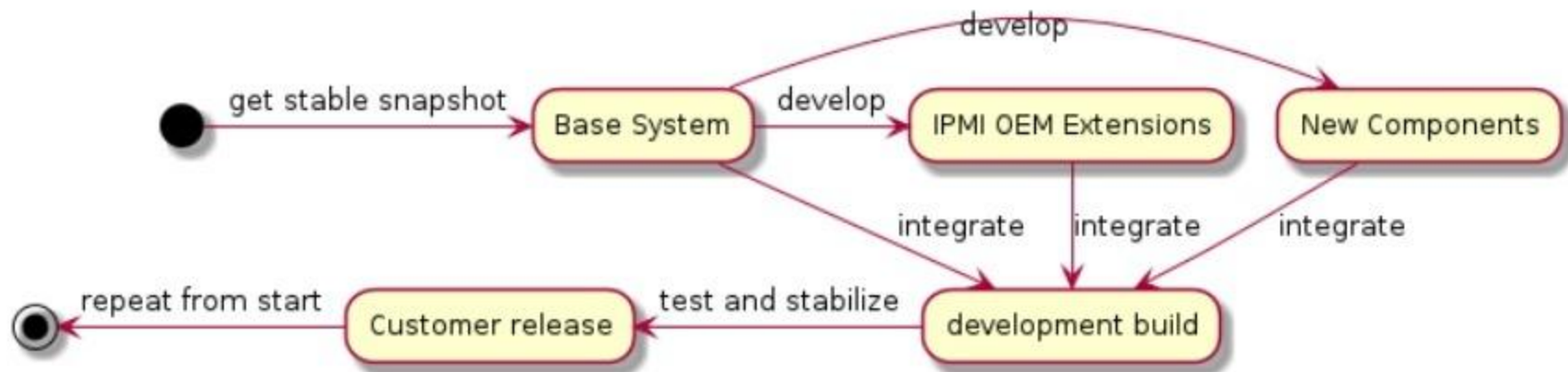
Package format similar to DEB, but not the same.

### **Eclipse-based IDE**

The screenshot displays the Visual Studio IDE with the 'timeout.c' source file open. The code is a C program that implements a daemon process with various system calls and logging. The left pane shows the project structure with 'SPX' and 'timeout.c' selected. The right pane shows the 'SPX Console' output, which displays the progress of building the SPX package, including steps like 'Creating Info Contents', 'BUILD SRC', 'DEP', 'CC', 'LD', 'STRIP', 'CREATE BIN', and 'INSTALL BIN'. The console output also includes a warning about the image not being built when specific packages are used for build options.



## Development cycle



Very typical Embedded Linux development cycle (simplified view):

- 1 Get base system snapshot and freeze it
- 2 Develop new components and IPMI OEM extensions

## FOSS legal questions

- Following the FOSS licenses
- Special policy for FOSS components using
- Consolidation of components legal status
- Rare upstream communication <sup>1</sup>
- FOSS component sources - by demand from support

## Demo 3

Development login via SSH.

Show typical Embedded Linux system.

Questions? Remarks?



shaping tomorrow with you

- Fujitsu Primergy servers: <http://www.fujitsu.com/fts/products/computing/servers/primergy/>
- iRMC S4 manual: <http://manuals.ts.fujitsu.com/file/11470/irmc-s4-ug-en.pdf>
- Emulex Pilot 3 iBMC specs: <http://www.emulex.com/products/controllers/management-controllers/pilot-3/>